

# Real-time Scheduling Open Problems Seminar (RTSOPS 2018)

## Nested Locks in the Lock Implementation: The Real-Time Read-Write Semaphores on Linux



redhat®



Sant'Anna  
School of Advanced Studies – Pisa



UNIVERSIDADE FEDERAL  
DE SANTA CATARINA

Daniel B. de Oliveira<sup>1,2,3</sup>, Daniel Casini<sup>2</sup>, Rômulo S. de Oliveira<sup>3</sup>, Tommaso Cucinotta<sup>2</sup>, Alessandro Biondi<sup>2</sup>, and Giorgio Buttazzo<sup>2</sup>

Email: [bristot@redhat.com](mailto:bristot@redhat.com), [romulo.deoliveira@ufsc.br](mailto:romulo.deoliveira@ufsc.br),

{ [daniel.casini](mailto:daniel.casini@redhat.com), [tommaso.cucinotta](mailto:tommaso.cucinotta@redhat.com), [alessandro.biondi](mailto:alessandro.biondi@redhat.com), [giorgio.buttazzo](mailto:giorgio.buttazzo@redhat.com) } @santannapisa.it

# Real-time Linux

- Linux is a GPOS with RTOS ambitions
  - Preemptive
  - FIFO (TLFP) and Deadline (DLFP) schedulers
  - User-space locks with PIP & PCP
- PREEMPT-RT improves Linux's predictability by:
  - Making system as preemptive/schedulable as possible
  - Bounding priority inversions using PIP on kernel locks
  - Max (activation delay?) latency of 150  $\mu$ s

# Real-time Linux however

Due to Linux's GPOS nature, RT Linux developers are challenged to provide the predictability required for an RTOS, while not causing regressions on the general purpose benchmarks.

# In practice it means

- Developers cannot cause performance regressions
  - Throughput:
    - Two implementations: RT and non RT
      - A newer algorithm cannot cause - much - regression compared to the older one
  - Predictability:
    - Cannot increase the *latency*
      - e.g, cannot disable the preemption for a long period

# Consequences...

As a consequence, the implementation of some well known algorithms, like read/write semaphores, has been done using approaches that were exhaustively explored in academic papers.

IOW: it works, but...

# Read/write semaphores on Linux

## Read-side

```
down_read(&rw_semaphore) {
    /* enters in the read-side */
}

/*
 * Read-side critical section
 * Parallel with other readers
 * No writers
 */

up_read(&rw_semaphore) {
    /* leaves the read-side */
}
```

## Write-side

```
down_write(&rw_semaphore) {
    /* enters in the write-side */
}

/*
 * Write-side critical section
 * Exclusive access
 */

up_write(&rw_semaphore) {
    /* leaves the write-side */
}
```

# Read/write semaphores on Linux

```
struct rw_semaphore {  
    atomic_t      readers;  
    struct rt_mutex  rtmutex;  
};
```

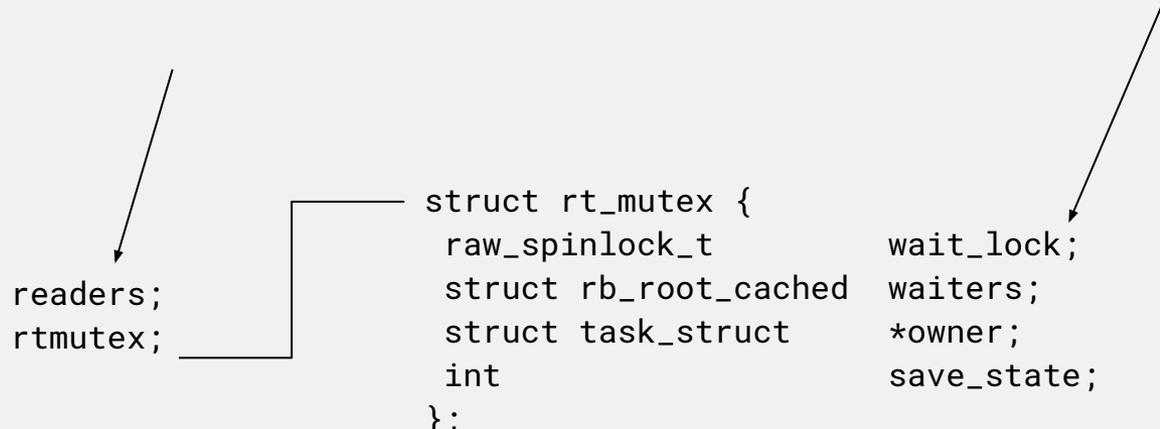
# Read/write semaphores on Linux

```
struct rw_semaphore {  
    atomic_t  
    struct rt_mutex  
};  
    readers;  
    rtmutex; }  
struct rt_mutex {  
    raw_spinlock_t  
    struct rb_root_cached  
    struct task_struct  
    int  
};  
    wait_lock;  
    waiters;  
    *owner;  
    save_state;
```

# Read/write semaphores on Linux

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struct rw_semaphore {  
    atomic_t  
    struct rt_mutex  
};
```

readers;  
rtmutex;



```
struct rt_mutex {  
    raw_spinlock_t  
    struct rb_root_cached  
    struct task_struct  
    int  
};
```

wait\_lock;  
waiters;  
\*owner;  
save\_state;

# Concurrent down operations

Atomic operation

```
down_read(rw_sem)
{
    if (++rw_sem->readers > 1)
        return /* enter the critical section */
    else
        rw_sem->readers--

    take rw_sem->rtmutex.wait_lock

    if (WRITER BIAS is not set) {
        rw_sem->readers++
        release rw_sem->rtmutex.wait_lock
        return /* enter in the critical section */
    }
    release rw_sem->rtmutex.wait_lock
    take rw_sem->rt_mutex
    rw_sem->readers++
    release the rw_sem->rt_mutex
    return /* enter in the critical section */
}
```

```
down_write(rw_sem) {
    take rw_sem->rtmutex
    clear READER BIAS
    if (rw_sem->readers != 0)
        suspend waiting for the last reader
    while(1) {
        take sem->rtmutex->wait_lock
        if (sem->readers == 0) {
            set WRITER BIAS
            release rw_sem->rtmutex->wait_lock
            return
        }
        release rw_sem->rtmutex->wait_lock.
        suspend waiting for the last reader
    }
    return
}
```

Mutex: ...  
Spin lock: ...

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Mutex: held  
Spin lock: ...

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Mutex: held  
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# Concurrent down operations

Atomic operation

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if (++rw_sem->readers > 1)
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take rw_sem->rtmutex.wait_lock
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```
release rw_sem->rtmutex.wait_lock
```

```
take rw_sem->rt_mutex
```

```
rw_sem->readers++
```

```
release the rw_sem->rt_mutex
```

```
return /* enter in the critical section */
```

```
}
```

down\_write(rw\_sem) {

```
take rw_sem->rtmutex
```

```
clear READER BIAS
```

```
if (rw_sem->readers != 0)
```

```
    suspend waiting for the last reader
```

```
while(1) {
```

```
take sem->rtmutex->wait_lock
```

```
if (sem->readers == 0) {
```

```
set WRITER BIAS
```

```
release rw_sem->rtmutex->wait_lock
```

```
return
```

```
}
```

```
release rw_sem->rtmutex->wait_lock.
```

```
suspend waiting for the last reader
```

```
}
```

```
return
```

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Spin lock: ...

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# Concurrent down operations

A task taking a write lock,  
With a nested mutex  
With a nested spin-lock.

Mutex: held  
Spin lock: held

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    return
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```

# Open Issues

1) Implementing in Linux state-of-the-art protocols for heterogeneous nested locks and developing novel analysis techniques

# Shared memory nested critical sections

- B. C. Ward and J. H. Anderson, “**Supporting nested locking in multiprocessor real-time systems,**” in Real-Time Systems (ECRTS), 2012 24th Euromicro Conference on, 2012, pp. 223–232.
  - Proposed real-time nested locking protocol (RNLP), with the related *asymptotic* analysis.
- B. C. Ward and J. H. Anderson, “**Fine-grained multiprocessor real-time locking with improved blocking,**” in Proceedings of the 21st International Conference on Real-Time Networks and Systems, ser. RTNS '13, 2013.
  - Conceived to deal with heterogeneous nested critical sections: Block + Spinning (short-on-long)

# Shared memory nested critical sections

- C. E. Nemitz, T. Amert, and J. H. Anderson, “**Real-time multiprocessor locks with nesting: Optimizing the common case,**” in Proceedings of the 25th International Conference on Real-Time and Network Systems (RTNS 2017), 2017
  - nested read/write spin lock with **fast path!**
- A. Biondi, A. Weider, and B. Brandenburg, “**A blocking bound for nested fifo spin locks,**” in Real-Time Systems Symposium (RTSS), 2016, pp. 291–302.
  - Graph abstraction is introduced to derive a fine-grained analysis, not based on asymptotic bounds for FIFO *non-preemptive* spin locks.

# Linux's locking needs

- Sleeping:
  - Nested blocking (rt mutexes)
  - Nested read/write (rw semaphores)
- Busy-wait:
  - Nested read/write spin (rw lock)
  - Nested spinlock (raw spin lock)
  
- Fast path is important
- Schedulers: TLFP, JLFP & IRQ/NMI
- Arbitrary affinities

2) The design of specialized analysis techniques accounting for specific implementations of complex types of locks (e.g., the aforementioned read/write lock in Linux).

3) finding more efficient locking protocols, accounting for both general purpose benchmark performance (i.e., average-case behavior, needed by the GPOS nature of Linux) and predictability.

Questions?

Thanks!